

# Computing Loops with at Most One External Support Rule for Basic Logic Programs with Arbitrary Constraint Atoms

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1 Motivations and Preliminaries

2 Our Work

3 Concluding Remark

- Previous work has shown that:
  - For normal and disjunctive programs, the well-founded models can be computed by **unit propagation** on **program completion** and **loop formulas of loops with no external support**.
  - When **loop formulas of loops with exactly one external support** are added, consequences beyond the well-founded model can be computed, which sometimes can significantly speed up answer set computation.
- We extend this approach to basic logic programs with abstract constraint atoms.

- An *abstract constraint atom* (*c-atom*)  $A$  is an expression of the form  $(D, C)$ , where  $D$  is a finite set of atoms and  $C \subseteq 2^D$ . Specially,  $A_d = D$  and  $A_c = C$ .
- A *basic logic program with c-atoms* (*logic program* or *program*) is a finite set of *rules* of the form

$$a \leftarrow A_1, \dots, A_k, \text{not } A_{k+1}, \dots, \text{not } A_n \quad (1)$$

where  $a$  is an atom and  $A_i$ 's are c-atoms.

- The notions of *r-answer set* and *c-answer set* are defined in (Son et al. JAIR 2007).

# Loops and Loop Formulas

- *A compact representation of c-atoms*: Let  $S$  and  $J$  be two disjoint sets of atoms,  $S \uplus J = \{S' \mid S \subseteq S' \text{ and } S' \subseteq S \cup J\}$ .  $S \uplus J$  is *maximal* in  $A$  if  $S \uplus J \subseteq A_c$  and there is no other sets  $S'$  and  $J'$  s.t.  $S' \uplus J' \subseteq A_c$  and  $S \uplus J \subset S' \uplus J'$ .  $A_c^*$  denotes the set of all maximal  $S \uplus J$  in  $A$
- The *dependency graph*  $G_P$  of a basic program  $P$  is a directed graph for atoms.  $(u, v)$  is a directed edge if there is a rule  $r \in P$  such that  $u = \text{head}(r)$  and  $v \in S$ , for some  $S \uplus J \in A_c^*$  and  $A \in \text{body}(r)$ .
- A set  $L$  of atoms is called a *loop* of  $P$ , if  $L$ -induced subgraph of  $G_P$  is strongly connected.

- Let

$$\pi_A(L) = \bigvee_{S \uplus J \in A_c^*} S \wedge \neg(A_d \setminus (S \cup J)),$$

$$\text{where } A_c^*|L = \{S \uplus J \in A_c^* \mid L \cap S = \emptyset\},$$

$$\sigma_A = \bigvee_{S \uplus J \in A_c^*} S \wedge \neg(A_d \setminus (S \cup J)),$$

- For a basic rule  $r$  of the form (1), we define the formula

$$\theta_L(r) = \pi_{A_1}(L) \wedge \cdots \wedge \pi_{A_k}(L) \wedge \neg\sigma_{A_{k+1}} \wedge \cdots \wedge \neg\sigma_{A_n}.$$

- A rule  $r \in P$  is an *external support* of  $L$  if  $\text{head}(r) \in L$  and  $\theta_L(r) \not\equiv \perp$ .
- The *loop formula* for  $L$  of  $P$ , denoted  $IF_P(L)$ , is defined as

$$\bigvee_{a \in L} a \supset \bigvee_{r \in R^-(L)} \theta_L(r)$$

where  $R^-(L)$  is the set of external support rules of  $L$ .

- The *completion* of a basic program  $P$ , denoted by  $Comp(P)$ , consists of the following formulas:
  - $\bigwedge_{A \in pos(r)} \sigma_A \wedge \bigwedge_{A \in neg(r)} \neg \sigma_A \supset head(r)$ , for each  $r \in P$ ;
  - $a \supset \bigvee_{r \in P, head(r)=a} \left( \bigwedge_{A \in pos(r)} \sigma_A \wedge \bigwedge_{A \in neg(r)} \neg \sigma_A \right)$ , for each  $a \in \mathcal{A}$ .

## Theorem 1

Let  $P$  be a basic program. A set  $M \subseteq \mathcal{A}$  is an  $r$ -answer set of  $P$  iff  $M$  is a model of  $Comp(P) \cup \{LF_P(L) \mid L \text{ is a loop of } P\}$ .



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**Function**  $ML_0(P, X, S)$

$ML := \emptyset$ ;  $G :=$  the  $S$  induced subgraph of  $G_P$ ;

For each strongly connected component  $L$  of  $G$ :

**if**  $R^-(L, X) = \emptyset$  **then** add  $L$  to  $ML$

**else** append  $ML_0(P, X, L \setminus \{head(r) \mid r \in R^-(L, X)\})$  to  $ML$ .

**return**  $ML$ .

Let us define

$$loop_0(P, X) = \bigcup_{L \in ML_0(P, X, \mathcal{A})} \neg.L.$$

# An iterative procedure

Input: A basic logic program  $P$

Output: A set of literals  $X$

- 1 let  $X := \emptyset$ , compute the completion of  $P$  and convert it to set of clauses  $C$ ;
- 2 compute the loop formulas of the loops that have no external support rules under  $X$ , then add them to  $C$ ;
- 3 apply unit propagation to  $C$ , append the computed consequences to  $X$ ;
- 4 go back to step 2 until it does not produce any new consequences.

- The above procedure computes the well-founded model in [Wang et al. 2012].
- The procedure can be improved to compute the (ultimate) well-founded semantics of [Pelov et al. 2007] for aggregate programs with only monotonic aggregate atoms.
- If we add loop formulas of loops that have exactly one external support rule in the above procedure, it computes a super set of the well-founded model.

$$T^P(X) = UP(comp(P) \cup loop_0(P, X) \cup loop_1^u(P, X) \cup X).$$

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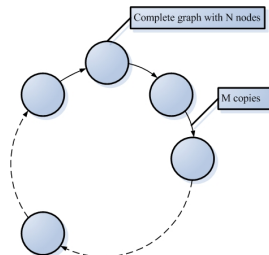
# Some Experiments

- We implement the previous procedure for program  $P$  that can be accepted by `lparse`. It first computes the least fixpoint of the  $T^P$  operator, denoted  $T(P)$ , and then adds  $\{\leftarrow \text{not } a \mid a \in T(P)\} \cup \{\leftarrow a \mid \neg a \in T(P)\}$  to  $P$ .
- We run our procedure on the familiar Hamiltonian Circuit (HC) problem encoded with the following cardinality constraints:

$\leftarrow 2\{dhc(X, Y) : arc(X, Y)\}, vertex(Y).$

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- The graphs have the structure:



# Experiment Results

| Problem | smodels | smodels <sub>T</sub> | clasp  | clasp <sub>T</sub> | <i>T</i> |
|---------|---------|----------------------|--------|--------------------|----------|
| 10x10   | 31.86   | 17.12                | 0.05   | 0.02               | 0.05     |
| 10x20   | -       | 175.28               | 0.04   | 0.06               | 0.11     |
| 10x30   | -       | 452.39               | 0.07   | 0.07               | 0.18     |
| 10x40   | -       | -                    | 0.10   | 0.11               | 0.26     |
| 10x50   | -       | -                    | 0.22   | 0.19               | 0.31     |
| 20x10   | -       | -                    | 18.45  | 5.76               | 0.44     |
| 20x20   | -       | -                    | 113.89 | 91.71              | 0.93     |
| 20x30   | -       | -                    | 96.12  | 18.83              | 1.34     |
| 20x40   | -       | -                    | 77.22  | 2.52               | 1.89     |
| 20x50   | -       | -                    | 422.37 | 201.61             | 2.38     |

Table : Run-time Data for smodels and clasp.

- $M \times N$ : a graph with  $N$  copies of the complete graph with  $M$  nodes.
- It shows that for most programs, information from  $T(P)$  makes both smodels and clasp run faster, when lookahead operators are turned off.

# Our contribution

- We extended the idea to basic logic programs with abstract constraint atoms.
- We gave algorithms for computing loop formulas of loops with at most one external support rule for basic logic programs.
- We considered how they, together with the program completion, can be used to deduce useful consequences of a logic program under unit propagation.
- We related the consequences computed here to the well-founded semantics in [Wang et al. 2012] and [Pelov et al. 2007].
- We showed that the loop formula approach for basic logic programs with c-atoms can also benefit answer set computation for some problems with a certain type of structure.



# Thank you!



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Pelov, N., Denecker, M., and Bruynooghe, M.

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